

Lecture 20: Linear Contextual Bandits

1) Setting

Our simplified MDP setting consists of:

- contexts $x \in \mathcal{X} \subseteq \mathbb{R}^d$
drawn from distribution $D \in \Delta(\mathcal{X})$ $x_t \sim D$
- actions "arms" $a \in \mathcal{A} = \{1, \dots, K\}$
- rewards $r_t = r(x_t, a_t)$ with
 $\mathbb{E}[r(x, a)] = \gamma_a(x) = \Theta_a^T x$ linear function
- Horizon T

Goal: find a policy $a_t = \pi(x_t)$ that achieves low regret.

$$R(T) = \sum_{t=1}^T \mathbb{E} \left[\underbrace{\max_a \Theta_a^T x_t}_{\gamma_*(x), a_*} - \Theta_{a_t}^T x_t \right]$$

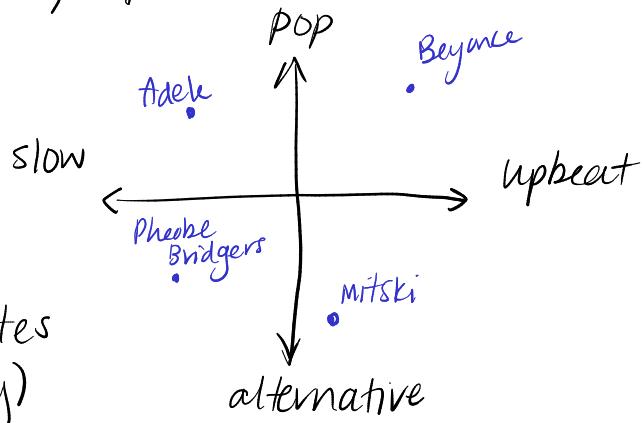
Example: music recommendation

arms a are artists

$\Theta_a \in \mathbb{R}^d$ represents attributes

$x \in \mathbb{R}^d$ represents a user's

affinity towards the attributes
(observed from listening history)



Last lecture we considered an explore-then-commit algorithm for general function approximation/supervised learning

$$a_t = \arg\max_a \hat{y}_a(x_t) \quad \text{where}$$

$$\hat{y}_a = \arg\min_{y \in M} \sum_{i=1}^N (y(x_i^a) - r_i^a)^2$$

↑
data collected during exploration phase.

Linear Regression

If we know that $y_a(x) = \theta_a^T x$ we can instantiate the general supervised learning framework with

$$M = \{y(x) = \theta^T x \mid \theta \in \mathbb{R}^d\}$$

In this case the learning problem is equivalent to

$$\hat{\theta}_a = \arg\min_{\theta} \sum_{i=1}^N (\theta^T x_i^a - r_i^a)^2$$

We will sometimes drop the a subscript in these notes.

Lemma: As long as $(x_i)_{i=1}^N$ span \mathbb{R}^d ,

$$\hat{\theta} = \underbrace{\left(\sum_{i=1}^N x_i x_i^T \right)}_A^{-1} \underbrace{\sum_{i=1}^N x_i r_i}_b = A^{-1} b$$

Proof:

$$\nabla_{\theta} \sum_{i=1}^N (\theta^T x_i - r_i)^2 = 2 \sum_{i=1}^N x_i (\theta^T x_i - r_i)$$

Setting the gradient equal to zero,

$$\underbrace{\left(\sum_{i=1}^N x_i x_i^T \right)}_A \theta = \underbrace{\sum_{i=1}^N x_i r_i}_b$$

The matrix on the left hand side is invertible if $(x_i)_{i=1}^N$ span \mathbb{R}^d

(why? Let $X = \begin{bmatrix} x_1^T \\ \vdots \\ x_N^T \end{bmatrix} \in \mathbb{R}^{N \times d}$. Then if x_i span \mathbb{R}^d , X has full row rank, $\text{rank}(X) = d$
 $\sum_{i=1}^N x_i x_i^T = X^T X \in \mathbb{R}^{d \times d}$ is full rank because $\text{rank}(X^T X) = \text{rank}(X) = d$. Therefore)
it is invertible.)

□

The matrix A is related to the empirical covariance

$$\Sigma = \mathbb{E}_{x \sim D}[xx^T] \quad \hat{\Sigma} = \frac{1}{N} \sum_{i=1}^N x_i x_i^T$$

We can relate $A = N\hat{\Sigma}$.

2) Interactive Demo - Jupyter Notebook

3) LinUCB Algorithm

Recall that last lecture we wanted to estimate conditional errors $\mathbb{E}[(\hat{\gamma}_{al}(x) - \gamma_{al}(x))^2 | x]$. Using the structure of the linear regression problem, we can do this.

We keep track of

$$A_t^a = \sum_{k=1}^t x_k x_k^\top \mathbb{1}\{a_k = a\}, \quad b_t^a = \sum_{k=1}^t x_k r_k \mathbb{1}\{a_k = a\}$$

$$\hat{\theta}_t^a = (A_t^a)^{-1} b_t^a$$

Alg: LinUCB

Initialize o mean & infinite confidence intervals

For $t=1, \dots, T$:

$$a_t = \underset{a}{\operatorname{argmax}} \hat{\theta}_t^a x_t + \alpha \sqrt{x_t (A_t^a)^{-1} x_t}$$

update $\hat{\theta}^{at}$, b^{at} , A^{at}

Geometric Intuition:

$$\underbrace{\hat{\theta}^T x}_{\text{large if } x \text{ and } \hat{\theta} \text{ are aligned}} + \underbrace{\alpha \sqrt{x^T A^{-1} x}}_{\text{large if } x \text{ is not aligned with much historical data}}$$

$$x^T A^{-1} x = x^T (\sum_{i=1}^N \hat{\theta}_i^T) x$$

$$= \frac{1}{N} \underbrace{x^T \sum_{i=1}^N \hat{\theta}_i^T x}_{\text{amount of data alignment w/ data}}$$

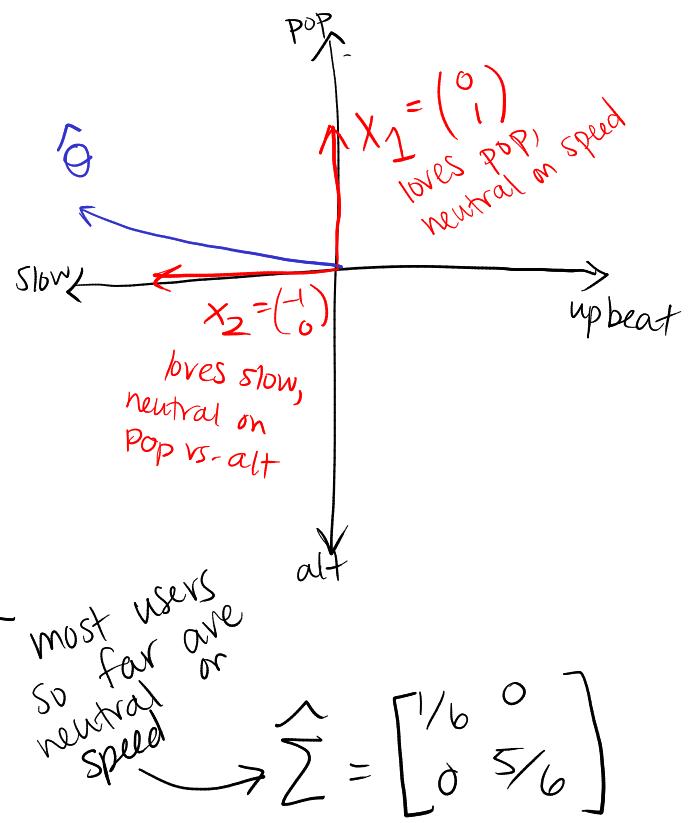
ex- $\hat{\theta}^T x_2 > \hat{\theta}^T x_1$
 ↓
 large alignment on speed
 ↓
 less alignment on pop

ex- if previous data is

$$(x_1, -x_1, x_1, x_1, -x_1, -x_2)$$

then $A^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & 1/5 \end{bmatrix}$

less sure on speed pretty sure about pop



$$\underbrace{x_1^T A^{-1} x_1}_{\text{more sure}} < \underbrace{x_2^T A^{-1} x_2}_{\text{less sure}}$$

Statistical Explanation:

Claim: With high probability (over noisy rewards)

$$\theta_a^T x \leq \hat{\theta}_a^T x + \alpha \sqrt{x^T A_a^{-1} x}$$

where α depends on probability & variance of rewards

Lemma: (Chebychev's Inequality)

for a random variable U with $\mathbb{E}(U) = 0$,

$$|U| \leq \beta \sqrt{\mathbb{E}(U^2)} \text{ with probability } 1 - 1/\beta^2$$

Proof: we will use chebychev's to show that w.h.p

$$\left| \underbrace{\hat{\Theta}_a^\top x - \Theta_a^\top x}_{u} \right| \leq \alpha \sqrt{\underbrace{x^\top A^{-1} x}_{\mathbb{E} u^2}}$$

1) compute expectation. Define $w_i = r_i - \mathbb{E}[r_i]$ so $r_i = \Theta_a^\top x_i + w_i$.

$$\begin{aligned}\Theta &= \left(\sum_{i=1}^N x_i x_i^\top \right)^{-1} \sum_{i=1}^N x_i (\Theta_a^\top x_i + w_i) \\ &= \cancel{\left(\sum_{i=1}^N x_i x_i^\top \right)^{-1}} \sum_{i=1}^N x_i x_i^\top \Theta_a + \left(\sum_{i=1}^N x_i x_i^\top \right)^{-1} \sum_{i=1}^N x_i w_i\end{aligned}$$

$$\Theta - \Theta_a = A^{-1} \sum_{i=1}^N x_i w_i$$

$$\text{therefore } \mathbb{E}((\Theta - \Theta_a)^\top x) = A^{-1} \sum_{i=1}^N x_i \mathbb{E}[w_i] = 0$$

2) compute variance

$$\begin{aligned}\mathbb{E}_{\Theta} \left[((\Theta - \Theta_a)^\top x)^2 \right] &= \mathbb{E}_{w_i} \left[x^\top A^{-1} \sum_{i=1}^N x_i w_i \cdot \sum_{i=1}^N x_i^\top w_i A^{-1} x \right] \\ &= x^\top A^{-1} \mathbb{E} \left[\sum_{i=1}^N \sum_{j=1}^N x_i x_j^\top w_i w_j \right] A^{-1} x\end{aligned}$$

The noise in rewards is iid so the expectation is 0 if $i \neq j$. Define σ^2 as variance of rewards.

$$= x^\top A^{-1} \sum_{i=1}^N x_i x_i^\top \underbrace{\sigma^2}_{= A!} A^{-1} x$$

$$= \sigma^2 x^\top A^{-1} x$$

Therefore, using Chebychev's, we have that w.p. $1 - \frac{1}{\beta^2}$,

$$|\Theta_a^T x - \hat{\Theta}_a^T x| \leq \underbrace{\beta \sigma}_{\alpha} \sqrt{x^T A^{-1} x}$$

Thus the upper bound of this confidence interval is $\hat{\Theta}^T x + \alpha \sqrt{x^T A^{-1} x}$

□